Duncan G. Cumming, Ph.D. (Camb.)

Expertise

- ITC Experience
- Power Supplies
- Electronic Hardware
- Embedded Control Systems
- GPS Systems
- Joystick Design (Games)
- RF Systems



Professional Summary

Dr. Duncan G. Cumming, Ph.D. (EE, Cambridge University, England, 1979) is the president of Emmanuel Avionics, Inc at San Pedro, California. He has been in the business of electronic design since 1979. Dr. Cummings' core business is the design of electronic controls for the Unmanned Air Vehicle (UAV) market, including inertial measurement, autopilots, electrical power controls, RF systems and video technology. These technologies are mostly applicable to the civilian market, although some UAVs do have military applications. Dr. Cumming has a wide scientific background, and is able to provide expert testimony and assess both the performance and the newness of various technologies. While this is primarily useful in Intellectual Property disputes, it has occasional applications in other types of cases.

Employment History

From: 1996 **Emmanuel Avionics. Inc.**

To: Present San Pedro, CA

Position: *President – Electronic hardware consulting.*

From: 1984 **Cambridge Electronic Design, Inc.**

To: 1996 San Pedro, CA

Position: Chief Executive Officer – Electronic hardware consulting.

From: 1982 **Unified Technologies, Inc.**

To: 1984 Los Angeles, CA

Position: Senior Systems Design Engineer. Designed video game software and

CRT display system.

From: 1979 **Hughes Aircraft Co.** To: 1982 Los Angeles, CA

Position: Member of Technical Staff – commissioned electron beam

microfabrication system

From: 1979 **Cambridge University Engineering Dept.**

To: 1979 Cambridge, UK

Position: Postgraduate Research Student – Researched revolutionary new e-beam

imaging system.

Consulting History

Dr. Cumming has a wide range of expertise acquired over the years. Clients have included everything from one man operations to Fortune 500 companies. Some of the major clients are shown below:-

From: 1984 Client:- Aero Vironment, Inc.

To: Present Simi Valley, CA

Duties: Design and construction of numerous electronics packages for

unmanned air vehicles.

Embedded Control Systems including Atmel and Motorola. Experienced using Integrated Development Environments.

Switched Mode Power Supplies. Over the years, Dr Cumming has worked on a wide variety of switched mode power supplies. From computer card supplies (5V) to high voltage (30kV), and some exotic supplies with input voltages of less than a volt. He has used most supply topologies at one time or another, for boost mode, buck mode and both. **RF Systems** including receiver design, video transmitter design, digital control systems and radio modems.

Transducers including accelerometers, integrated gyros, conventional rate gyros, pressure transducers, strain gauges and magnetometers. Inertial Measurement Units (IMU). Both design from scratch, and utilization of commercially available units.

Unmanned Air Vehicle Design, including both fixed wing and rotary types, on all scales from 6 inch wing span to 270 feet.

From: 1983 Client:- Hughes Aircraft Co

To: 1984 Torrance, CA

Duties: Enhancement and maintenance of electron beam microfabrication

system.

Magnetic Deflection Systems. High resolution deflection systems for electron beam microfabrication, raster mode and vector mode deflection systems for cathode ray tubes, and one combined system that did both

raster and vector deflection simultaneously.

From: 2009 Client:- Sage Cheshire, Inc

To: 2010 Lancaster, CA

Duties: Design and construction of space suit chest pack for Red Bull Stratos

high altitude parachuting record attempt.

Global Positioning System. Selection and interfacing of suitable GPS

receivers for a large variety of tasks, including supersonic speed

measurement using civilian GPS receivers.

From: 1986 Client:- Applied Research Associates, Inc.

To: 1989 Albuquerque, NM

Duties: Design and construction of numerous electronics packages for 70 foot

unmanned surveillance blimp.

Video Camera control systems. Pan/tilt units, gyro stabilized camera

mounts.

Autopilots. Dr Cumming has designed autopilot systems for fixed

wing, rotary, blimp, and balloon systems.

Infra Red, Visible Light, and Low Light video camera systems.

From: 1984 **Client:- Other**

Present

To:

Duties: Electronic Hardware Design Projects

RF design for underground pipe detection, metal detection, and other low frequency (VLF) applications.

Joystick Design and human factors engineering, including force operated joysticks, programmable joysticks, and "use in the air" joysticks (i.e. not connected to any fixed object).

Pneumatic Control Systems. Automatic braking and throttle control systems. Investigation of "sudden acceleration" problems.

Autonomous Vehicle Design. Dr. Cumming developed the interface units for a vehicle that entered the DARPA Grand Challenge, a government sponsored unmanned ground vehicle competition.

Rocket Payload Systems. Both sub-orbital and near-space systems. **Power Electronics.** Dr Cumming has designed 400Hz harmonic reduction systems for the Boeing 747 aircraft, high power oscillators (1MHz, 10kW), motor control systems, and heater control systems.

Magnetic Levitation Systems. Dr Cumming has designed everything from a simple overhead solenoid system to a complete levitation system operating entirely from below a flat table top, with no visible sensors.

High Voltage Pulsed Systems. Dr Cumming has worked with a 10kV, 3Amp, 50nS pulsed system for field emission cathodes.

High voltage DC systems. Dr Cumming has worked with a number of high voltage control systems in the electron beam microfabrication industry, up to 30kV. He is also familiar with the use of **thermionic tubes** in such control systems, one of the few surviving uses of the thermionic tube today.

Vacuum Systems. Dr Cumming has experience with both diffusion pumped high vacuum systems and ultra high vacuum ion pumped systems. He has worked with tungsten, LaB₆, and field emission cathodes and the associated high voltage equipment.

Litigation Support Experience

Date: 1996

Case Cambridge Electronic Design, Inc.

Project: Testified as the defendant in a contractual dispute with Cambridge

Electronic Design, Inc. This involved a successful petition to compel arbitration in superior court, and testimony (using telephone conference

calls) for the ensuing binding arbitration.

Status: Case closed, no damages awarded.

Date: 2010

Matter International Trade Commission Action

Project: Acted as a Consulting Expert Witness in a patent validity case involving

power supplies.

Status: My involvement complete, but case ongoing as of Oct, 2010

Date: 2011

Matter International Trade Commission Action

Project: Acted as a Testifying Expert Witness in a patent validity case involving

marine autopilots.

Status: Case settled on favorable terms following my testimony at deposition.

Date: 2012

Case Product Liability Case – Superior Court Of The State Of California

Project: Acted as a Testifying Expert Witness against a luxury automobile

manufacturer in a product liability case involving an automotive braking

system.

Status: Jury verdict against the auto manufacturer in March, 2012.

Date: 2012

Matter International Trade Commission Action

Project: Acted as a Testifying Expert Witness in a patent validity case involving

hand held computers.

Status: Case dropped prior to first deposition.

Date: 2012

Matter Patent Infringement Case – Delaware District Court

Project: Acted as a Consulting Expert Witness in patent validity matters

involving LCD displays and docking computers.

Status: My involvement complete, but case ongoing as of October, 2012

Patents

| Patent Number | Date Issued | <u>Title</u> |
|---------------|--------------|---|
| 7013.001 | May 24, 1996 | Cordless Free Floating Joystick (Provisional) |
| 13/741,558 | Pending | Method For Generating Tidal Energy Utilizing The Scalar |
| | | Gravitational Potential of Celestial Bodies. |

Education

| <u>Year</u> | <u>College/University</u> | <u>Degree</u> |
|-------------|-------------------------------|-------------------------------|
| 1979 | Cambridge University, England | Ph.D., Electrical Engineering |
| 1978 | Cambridge University, England | MA |
| 1974 | Cambridge University, England | BA |

Publications

Cumming, A.D.G. "A Method For Determining The Geometry Of Field Emitters" Optik, **49** No.1 (1977) 17-23.

Bishop, J.F., Cumming, A.D.G., Ferrari, R.L., Miller K.J. "Cambridge University Vatnajokull Expedition, 1977" Polar Record, **19** No. 118 (1978) 51-57.

Cumming, A.D.G., Smith, K.C.A. "Energy Spread And Fluctuations In Field Emitted Electron Beams" Microcircut Engineering ed. H. Ahmed, W.C. Nixon © Cambridge University Press (1980) 575-579

Cumming, A.D.G. "A High Speed, Noise Tolerant Edge Detection Algorithm Using A Low Bandwidth Signal Chain for E-Beam Registration" Microcircuit Engineering (Feb 1981)

Cumming, A.D.G. "A High Performance, Low Cost, Isolated Electron Current Amplifier" Scanning © G. Witzstrock Publishing House Inc., 2, (1979) 104-109

Professional Associations and Achievements

- Member, IEEE
- Fellow of Cambridge Philosophical Society